

# Glacial Ice and Offshore Structure Impacts under Wave and Current Excitation

Wenjun Lu/31.03.22

NTNU

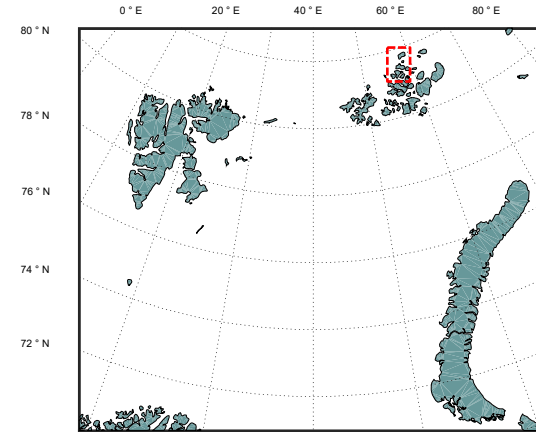
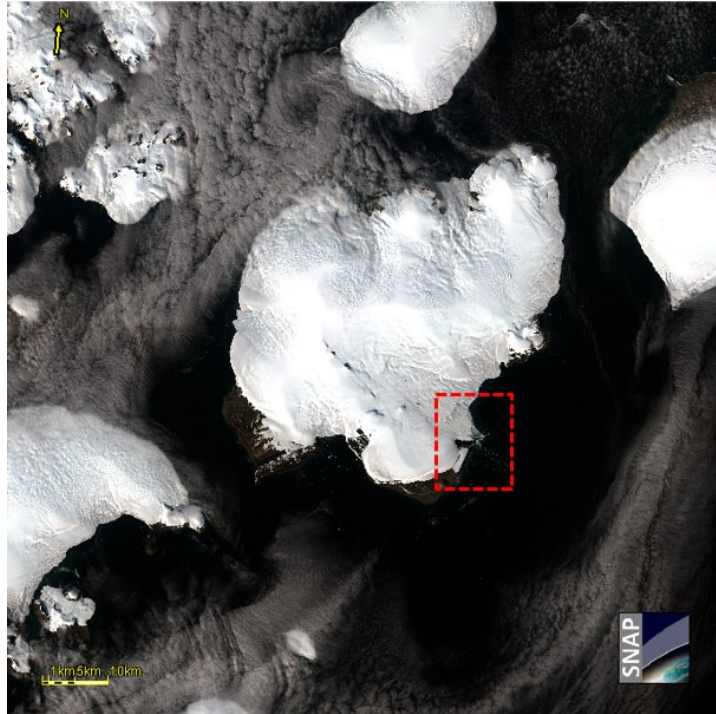
# Introduction



# Origin

Source

The birth of icebergs



Franz Josef Land (East)

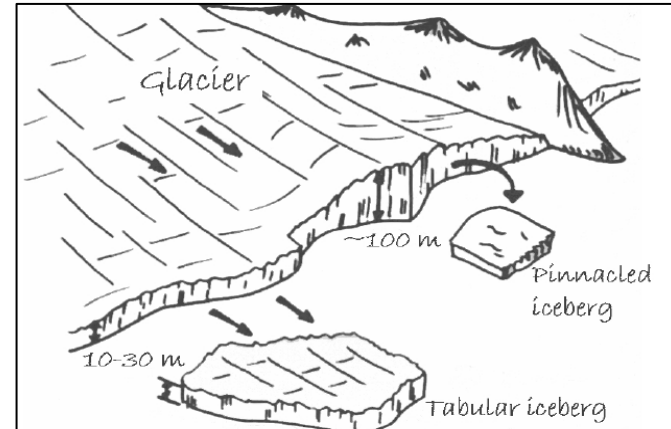
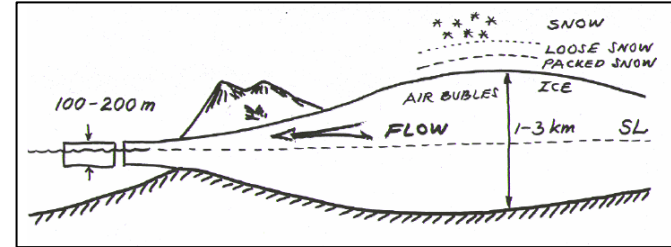
# Origin

Source

The birth of icebergs



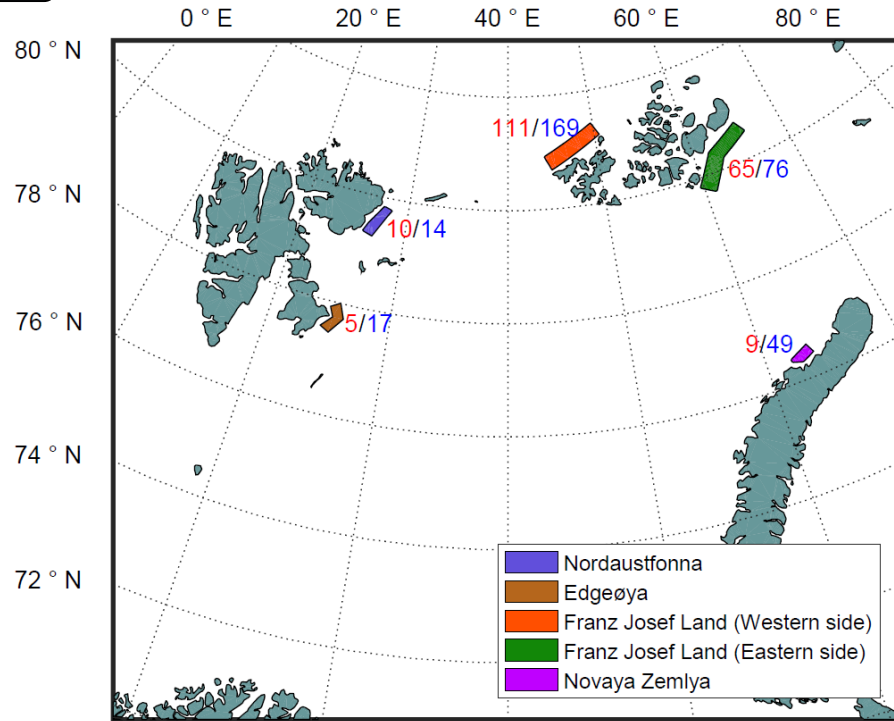
Franz Josef Land (East)



# Origin

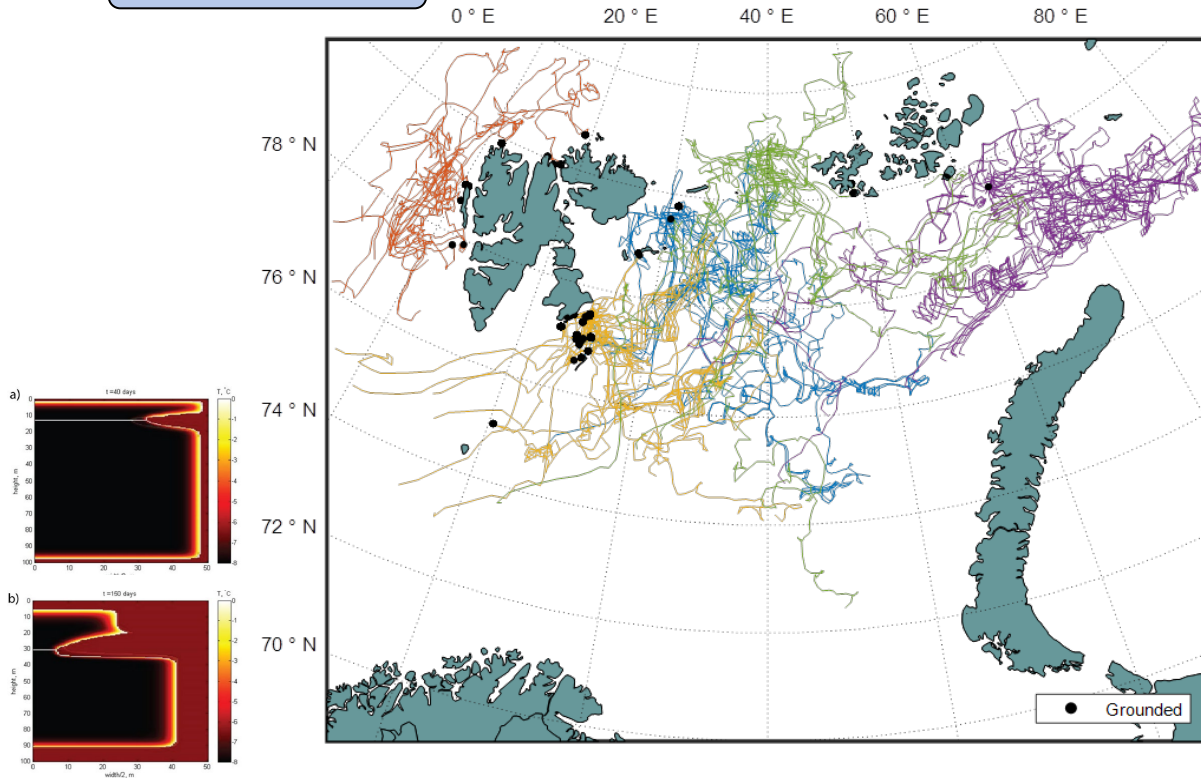
Source

## The birth of icebergs



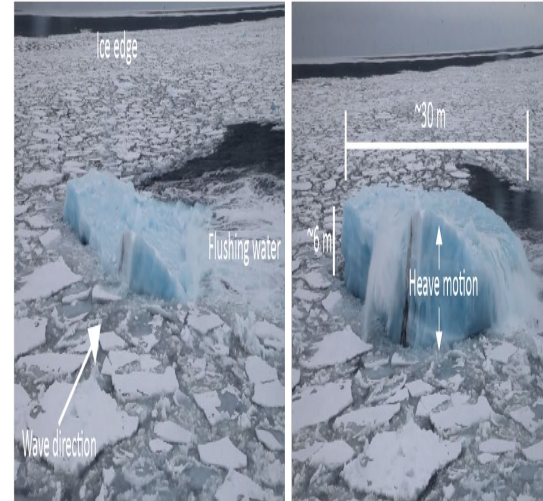
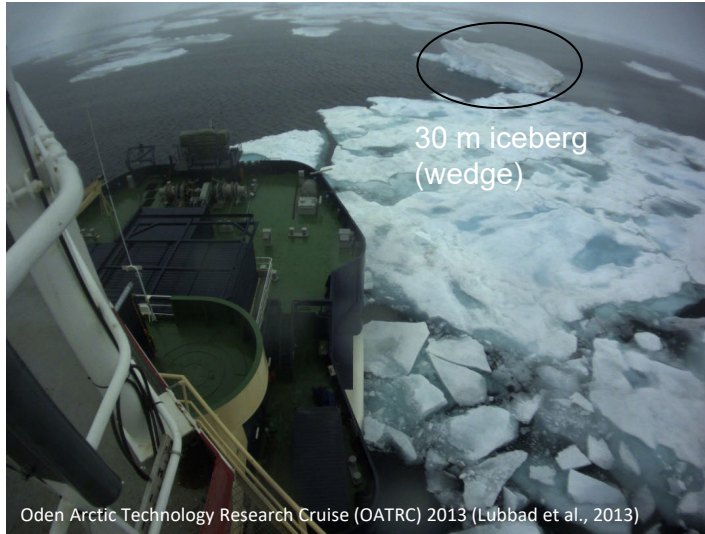
# Drift

## Far-field drift



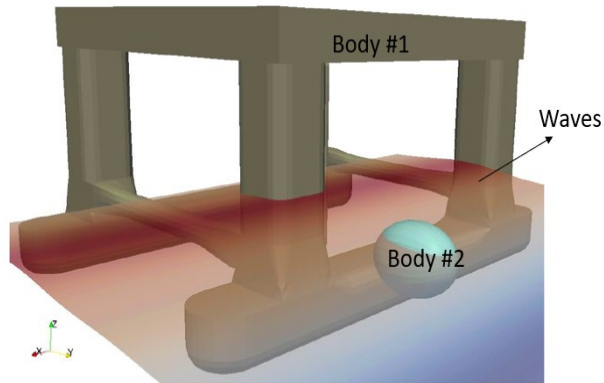
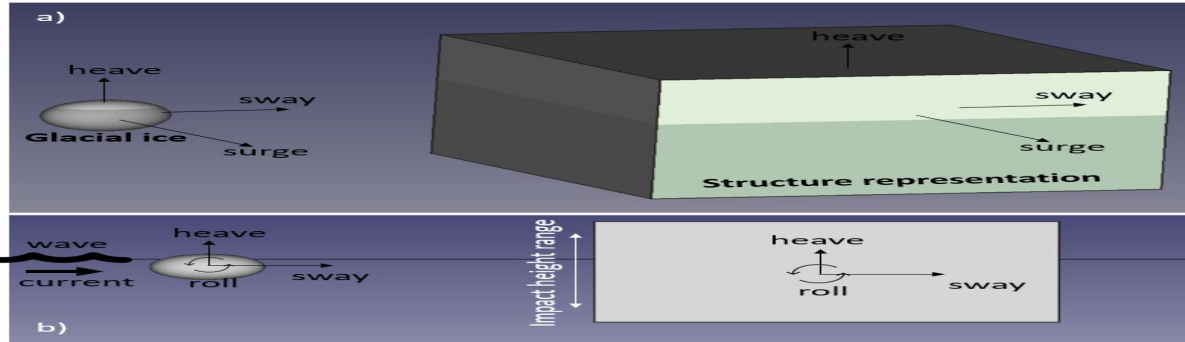
# Detection

When encounter does happen, we need to find out if we can detect these glacial ice features and thereafter apply ice management operations





# Motion in waves

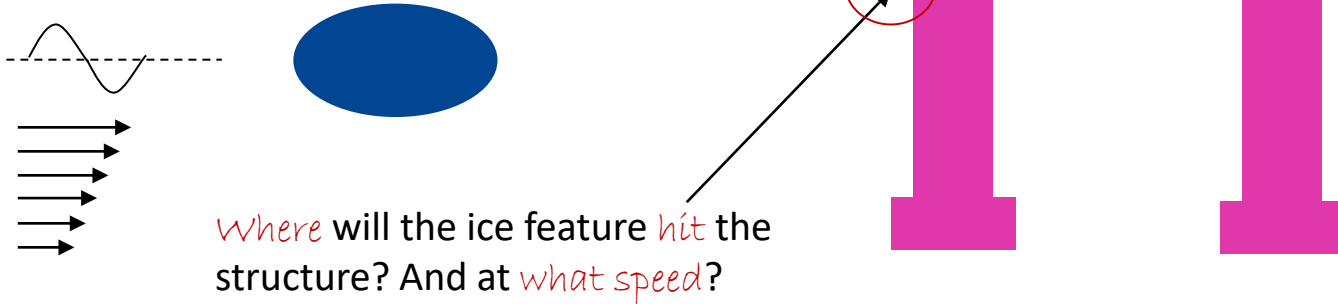


How are we going to solve this problem?

- Small glacial ice features are often interested as they are difficult to detect and manage
- Relative motion between the glacial ice and offshore structure can potentially lead to impact at unstrengthened location



## Principle sketch

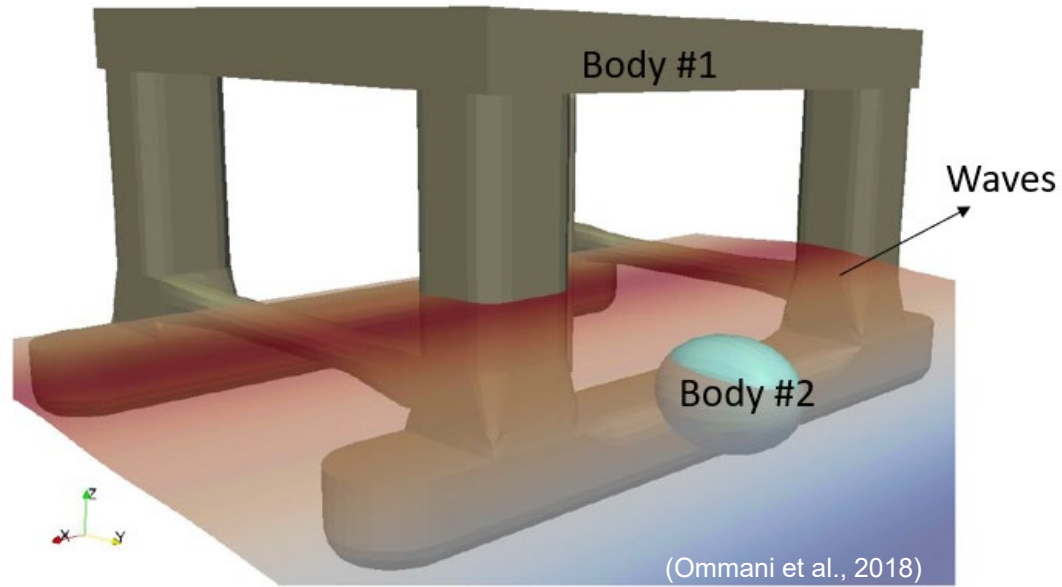


What is the fraction of the total incoming kinetic energy that will be *dissipated by crushing the ice and deforming the structure.*

We call this part: *demand for energy dissipation*

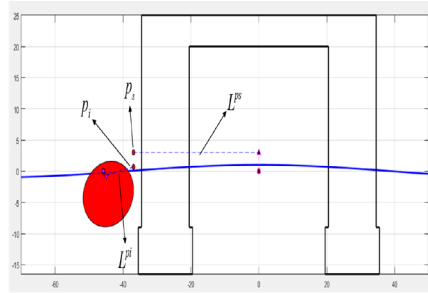
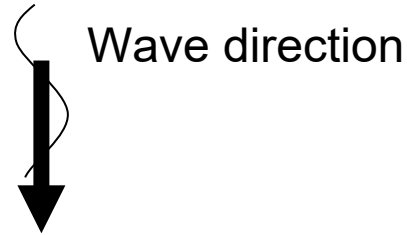
The analysis method to estimate this is called *External Mechanics*

The rest of the incoming kinetic energy will be transferred to rigid body motions

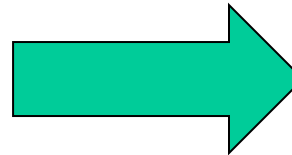


How are we going to solve this problem?

# Relative Motions



- Based on linear wave theory
- Response Amplitude Operators (RAOs) of both the structure and the glacial ice are available



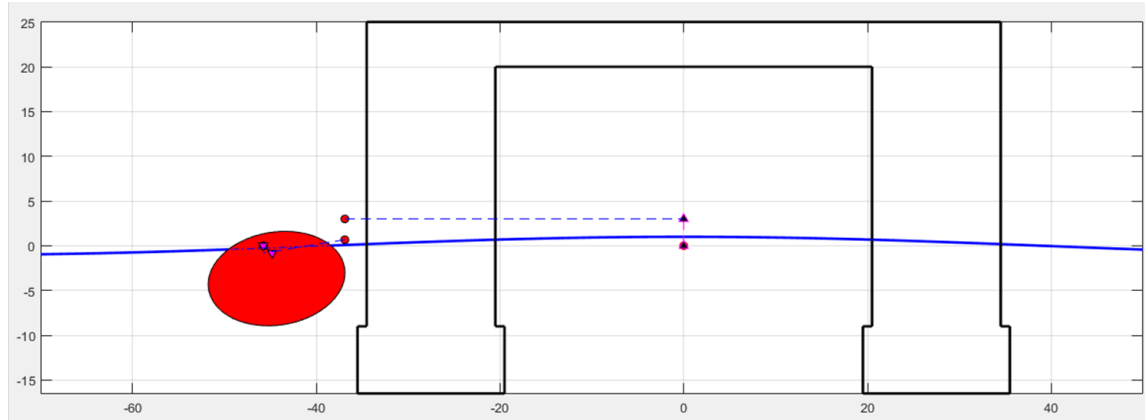
RAOs  $H(\omega, \beta)$

Wave elevation:  $\eta_w = \eta_0 \cos(\omega t - kx - \phi)$   
 Wave particle horizontal displacement:  $\eta_h = \eta_0 \sin(\omega t - kx - \phi)$

Point  $P_i$ 's heave with reference to structure 'M':  
 $\eta_i^M = |H_3^M(\omega)| \eta_0 \cos(\omega t - kx - \phi) + L^M |H_5^M(\omega)| \eta_0 \cos(\omega t - kx - \phi)$

Point  $P_i$ 's heave with reference to glacial ice 'M':  
 $\eta_i^I = |H_3^I(\omega)| \eta_0 \cos(\omega t - kx - \phi) + L^I |H_5^I(\omega)| \eta_0 \cos(\omega t - kx - \phi)$

# Relative Motions



Relative vertical displacement:

$$\Delta\eta = \eta_3^{ps} - \eta_3^{pi}$$

Point  $p_s$ 's sway velocity:

$$\dot{\eta}_2^{ps} = \omega \left| H_2^{p1}(\omega) \right| \eta_0 \cos(\omega t - kx - \phi)$$

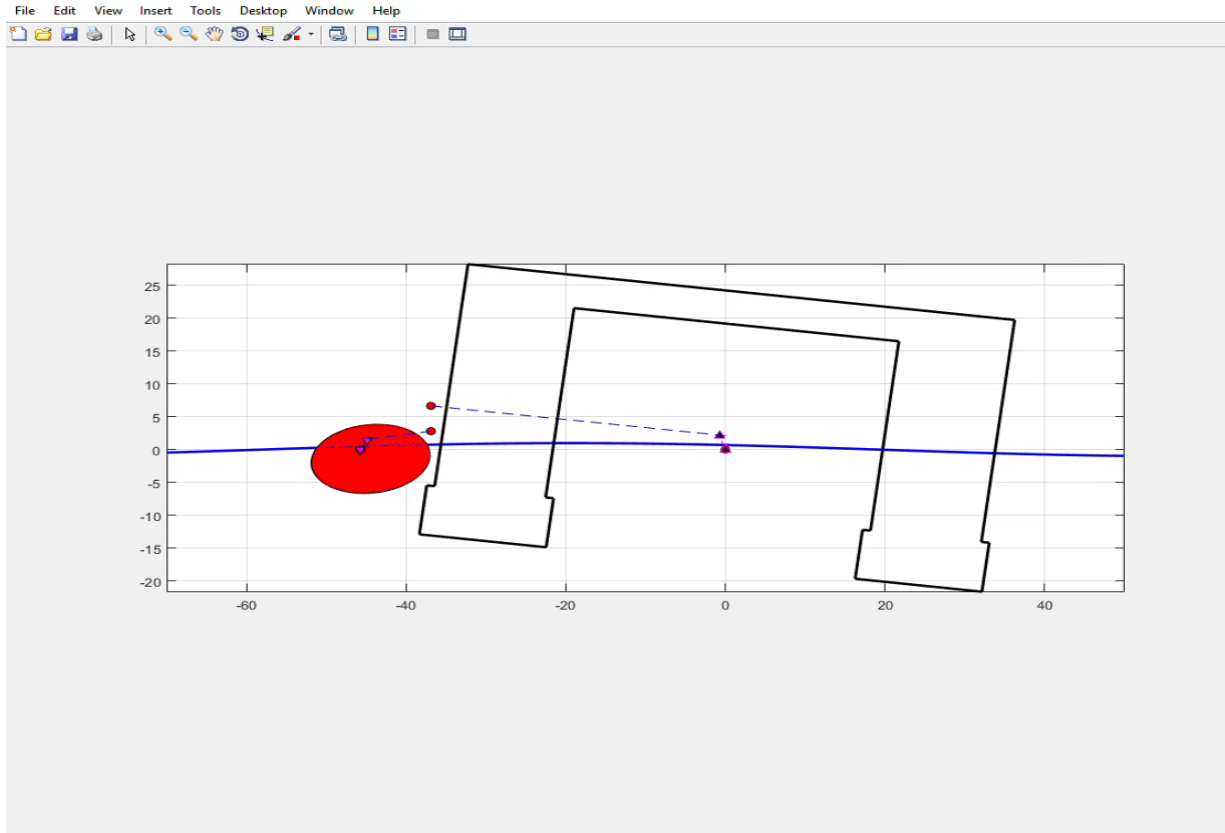
Point  $p_i$ 's sway velocity:

$$\dot{\eta}_2^{pi} = \omega \left| H_2^{pi}(\omega) \right| \eta_0 \cos(\omega t - kx - \phi)$$

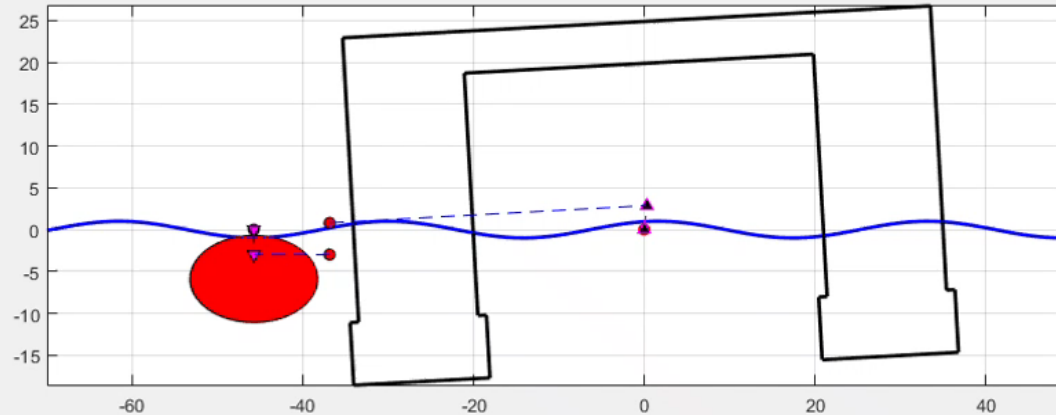
Relative vertical displacement:

$$\Delta\dot{\eta} = \dot{\eta}_2^{pi} - \dot{\eta}_2^{ps}$$

# Relative Motions

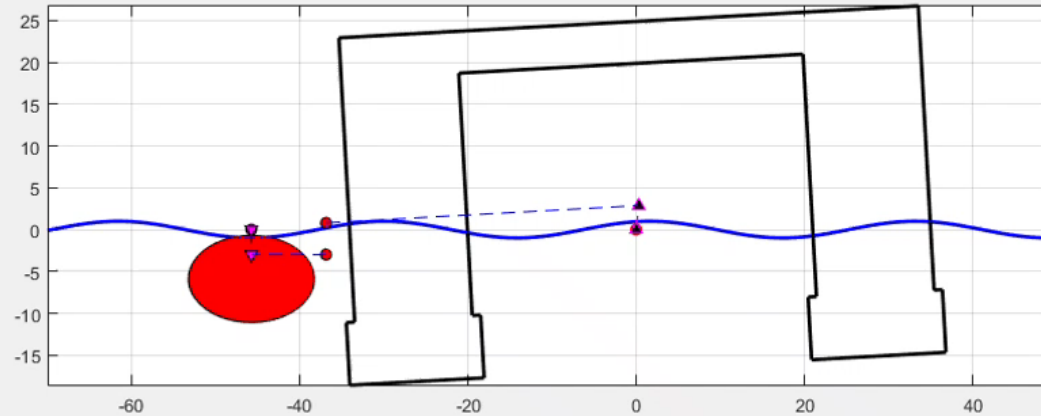


# Relative Motions



Implementing all previous equations, we can simulate the motion as above 'in time domain' or 'with various phase angle', e.g., a frequency component with a long wave

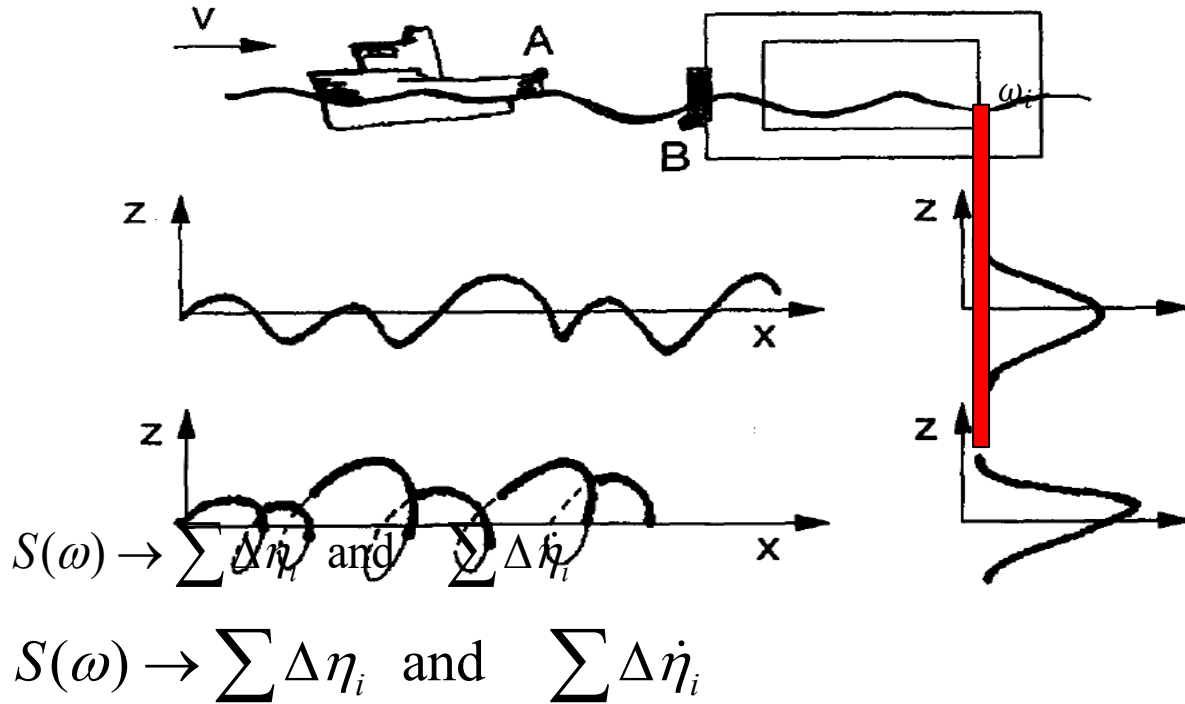
# Relative Motions



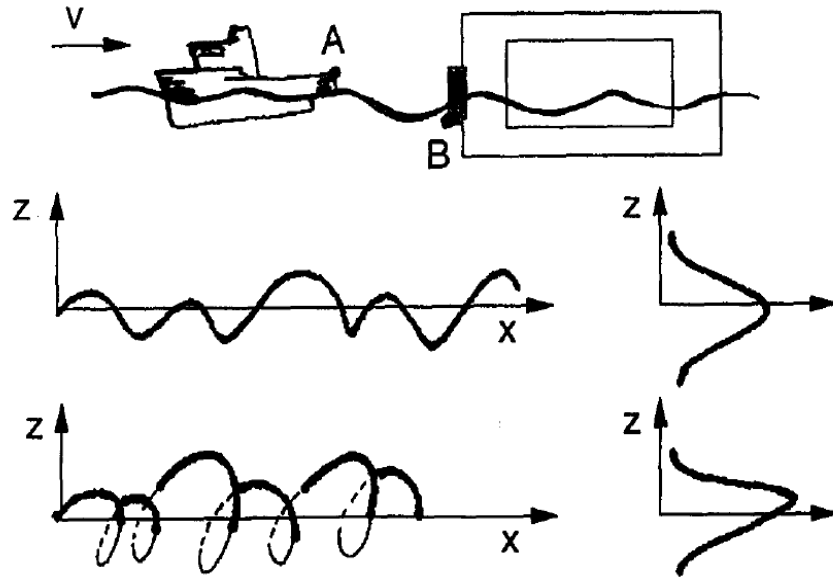
Implementing all previous equations, we can simulate the motion as above 'in time domain' or 'with various phase angle', e.g., a frequency component with a short wave



# Relative Motions



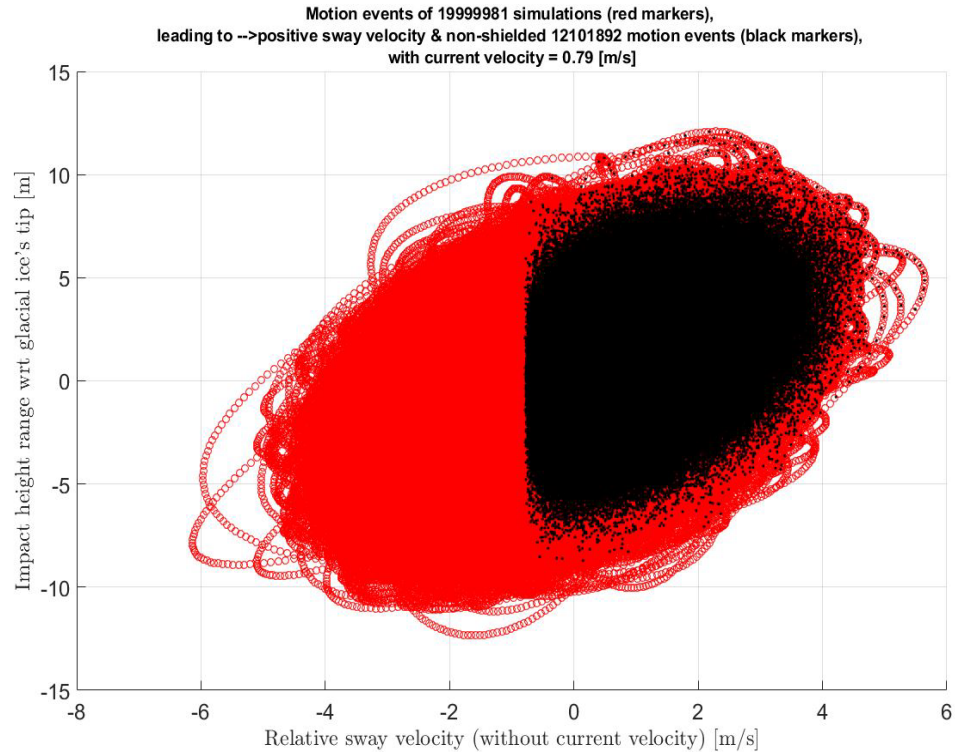
# Impact Events Sampling



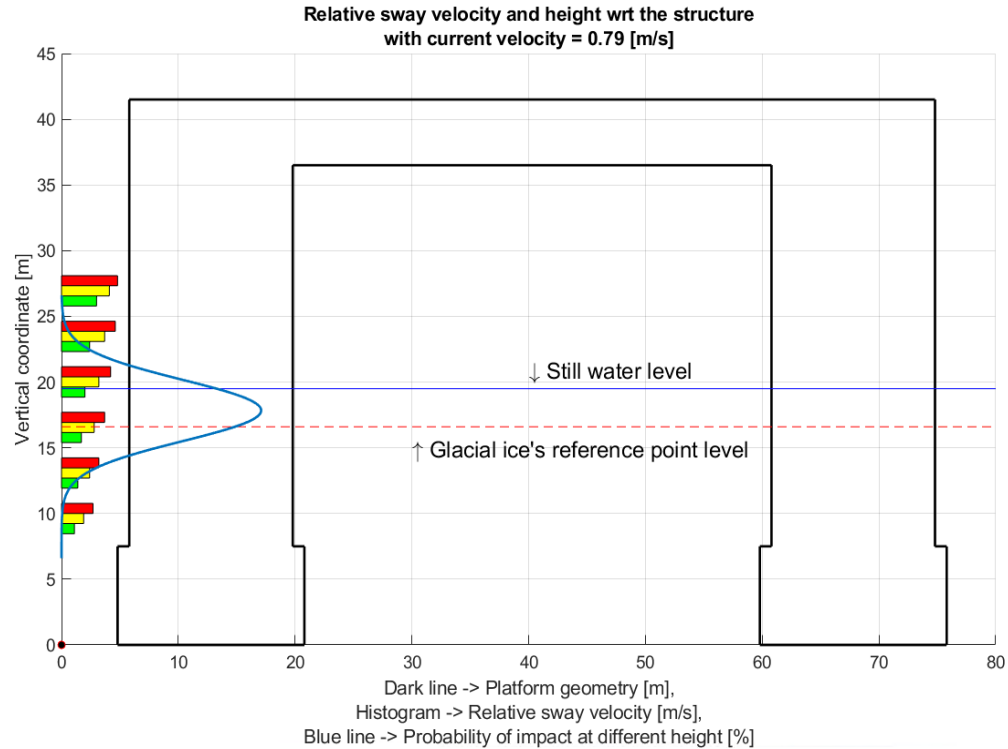
- Positive impact velocity
- Non-shielded trajectories

Fylling (1994)

# Impact Events Sampling

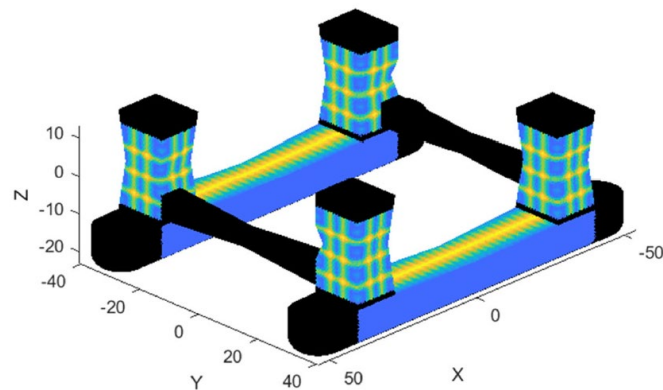
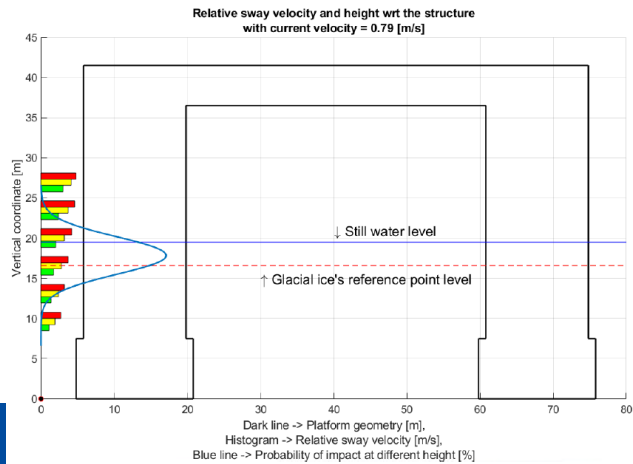
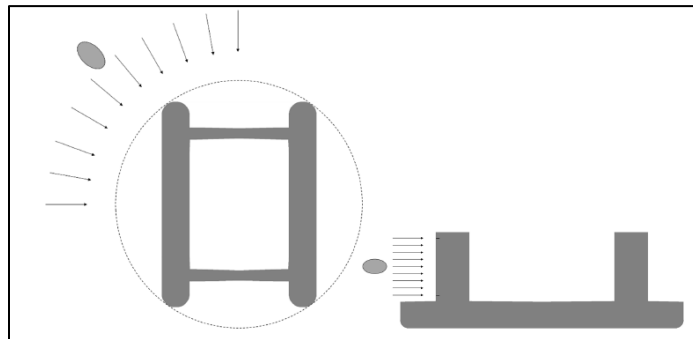
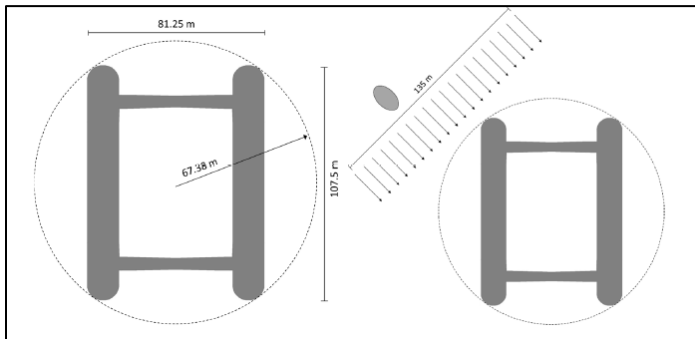


# Impact Events Sampling

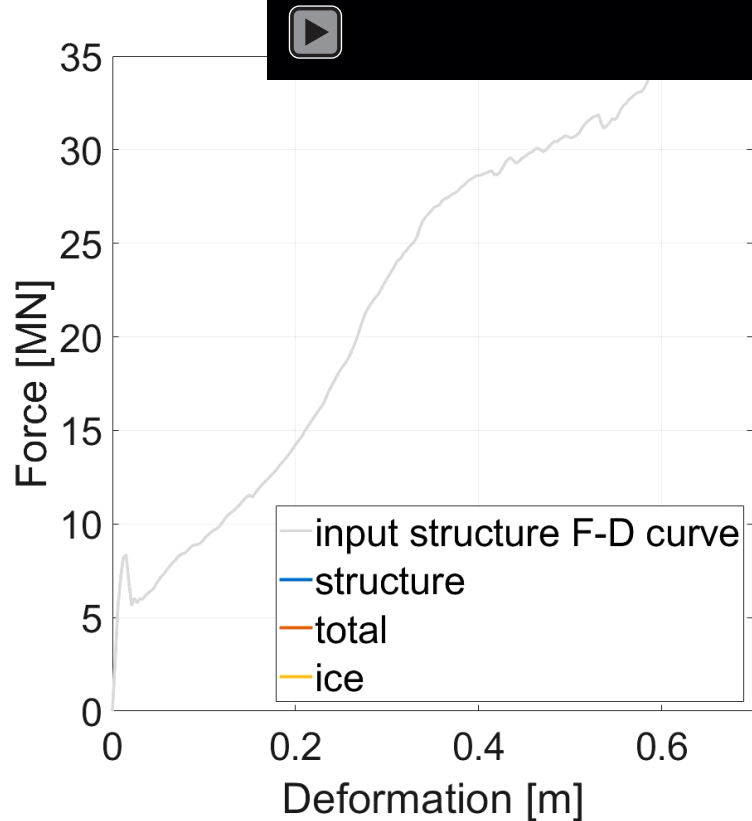
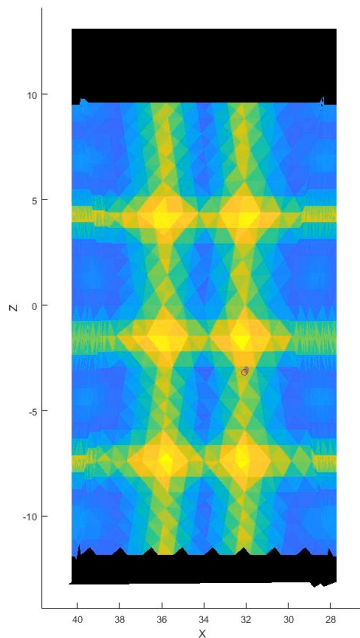


# Impact Analysis

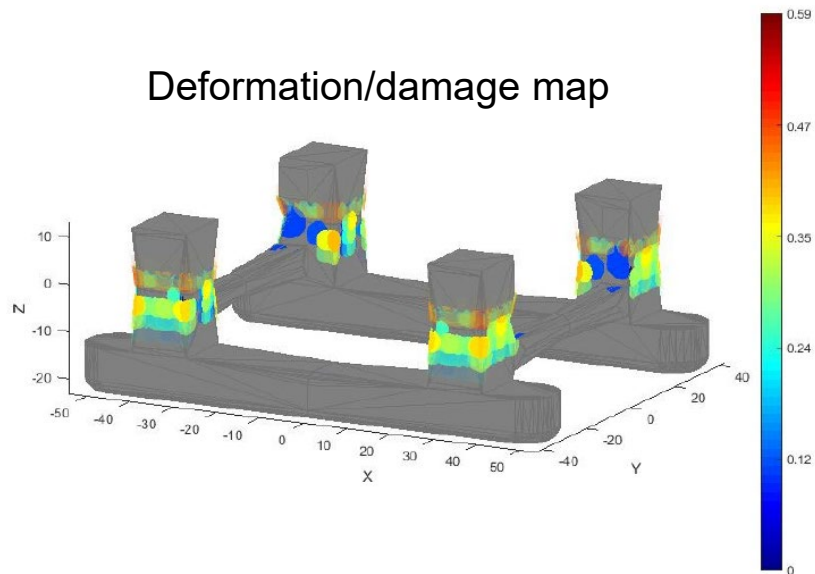
A combination of internal and external mechanics



# Impact Analysis



# Impact Analysis



- Maximum deformation is around 0.6 m
- 90% of the impact location has a deformation less than 0.36 m



# Conclusion

- The horizontal impact velocities increase with the impact height
- The most probable horizontal impact with the ice tip occurs around the SWL
  
- The proposed method is rather effective in construction a large amount of potential impact events (i.e., in the order of millions) from which, sensible distributions of impact information can be obtained.